³Canadian Wildlife Service

Agenda

- Overview / Study Area
- 2 Field Data
- 3 Methodology
- 4 Results
- 5 Conclusion and Questions









1 Overview / Study Area

- Three types of remote sensing data were collected from Tabusintac,
 NB over a three day period between September 24th and 26th, 2014
- Assess the accuracy/cost-effectiveness of these three eelgrass mapping approaches to inform resource management

- Single Beam Sonar (BioSonics)
- 8-band multispectral satellite imagery (Worldview-2)
- Topo-Bathy Lidar (Chiroptera II)



2 Methods - Groundtruth Data



Ground-truthing 24-26 Sept 2014

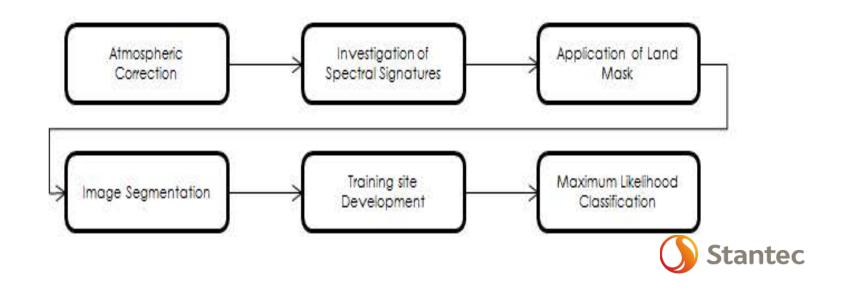
- 70 stations sampled
 - Stratified, random sampling
 - 4 x georef drop camera video quadrats per station
 - Presence/Absence
 - Percent cover
 - Algae
 - Depth sounding
- RTK GPS checkpoints (n = 24)
- Secchi disk
- Underwater light measurements (n = 10)
 - Diffuse attenuation coefficients



2 Methods - WorldView-2

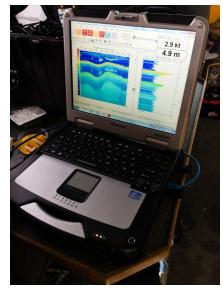
- 8-band image set collected on September 24th, 2014
 - Coastal Blue, Blue, Green, Yellow, Red, Red edge, NIR1, NIR2
- Spatial resolution of 0.46m (pan-sharpened)
- Combination of image segmentation and supervised classification





2 Methods - Single Beam Sonar

- BioSonics accuracy
 - Range: 1.7 cm ± 0.2% of depth
 - Positional: <3 m, 95% typical
- >8,500 data points
 - Bathymetry
 - Percent cover
 - Canopy height
 - Sediment classifications
- Transects oriented east-west spaced approximately 350 m apart in a north-south direction
 - total linear distance = 30.4 km
 - area of 5.45 km²







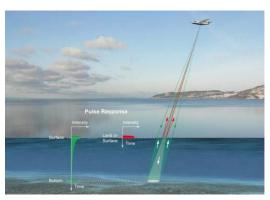
2 Methods - Lidar

Topo-Bathy Lidar (Chiroptera II)

 1064 nm near infrared (NIR) topo laser for ground returns and a green 515 nm bathy laser for seabed returns.

3 products produced, including:

- Lidar elevation (bathymetry)
- Lidar only eelgrass map
- Lidar-Aerial Photo Eelgrass map supplemented with Single Beam Sonar
- Full details in Webster et al. (in press)





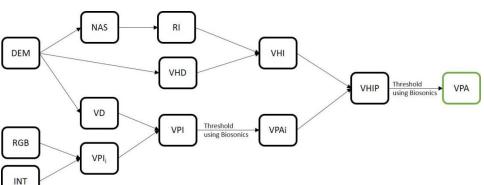
2 Integrated Assessment

BioSonics filled data gaps from WV-2/Lidar

depth-signal attenuation

BioSonics supplemented to gauge overall accuracy effect

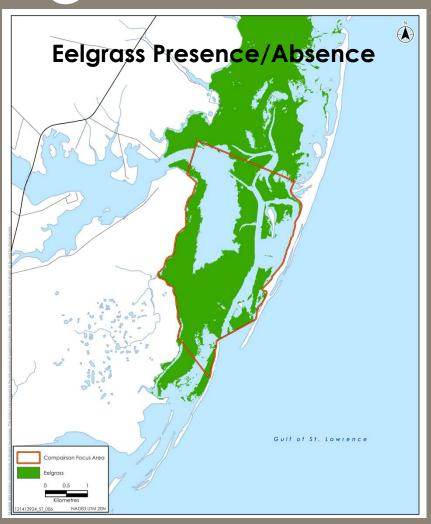
Super Maps!

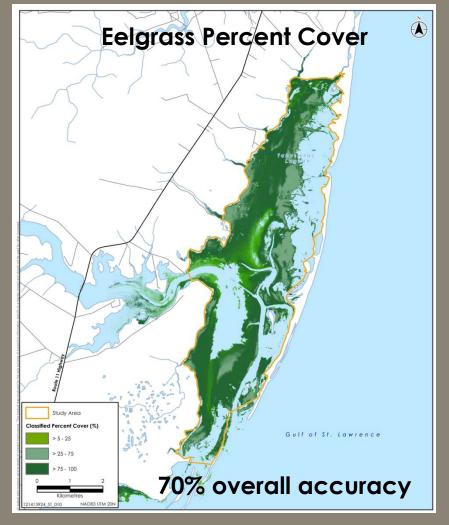






3 Results – WorldView-2



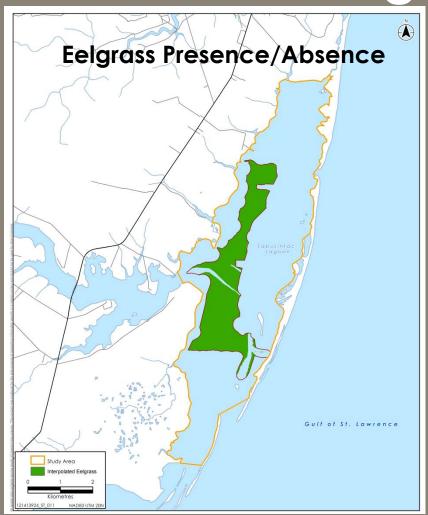


- Mostly medium-high density
- 15.8 km² of eelgrass

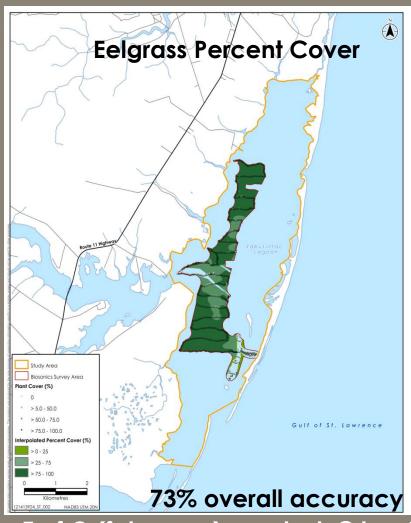
- E of O (false neg) greatest @ low PC
- Swath of "0% cover"



3 Results – Single Beam Sonar



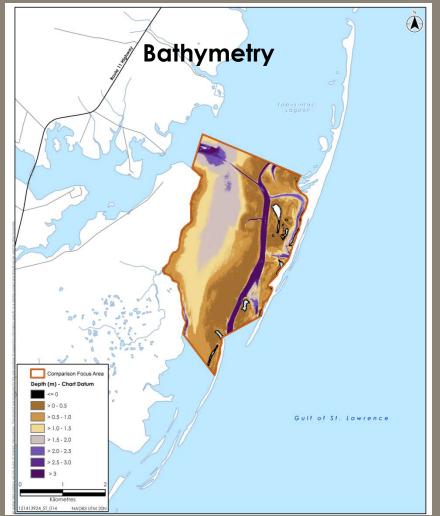
Mostly medium-high density
15.8 km² of eelgrass



- •E of O (false neg) greatest @ low PC
- •Swath of "0% cover" reduced



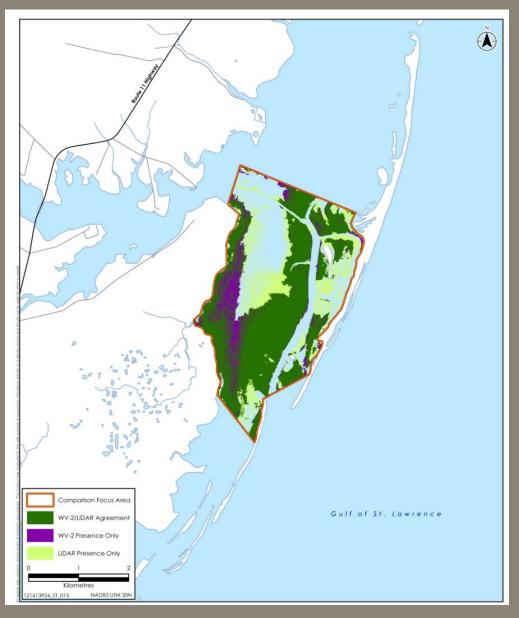
3 Results – LiDAR







3 Results – LiDAR

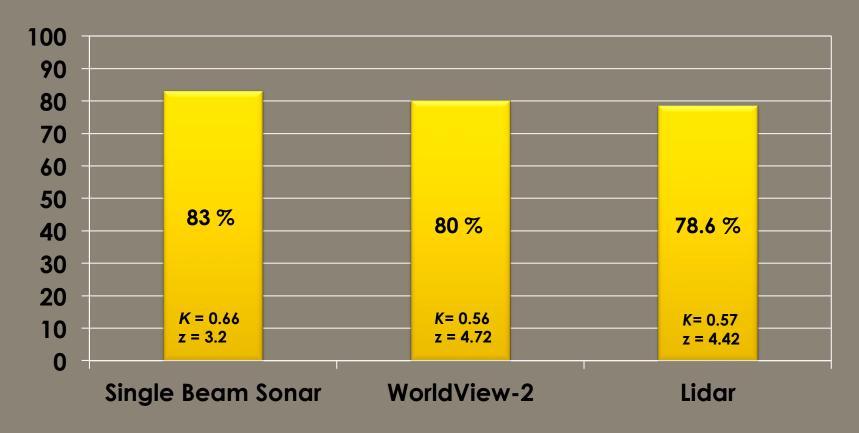


Comparable to WV-2, with slight disagreements
75% joint presence/
absence for lidar and WV-2





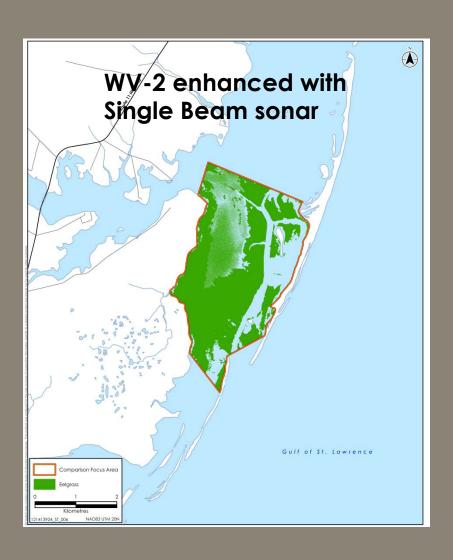
Overall Accuracy (%) P/A

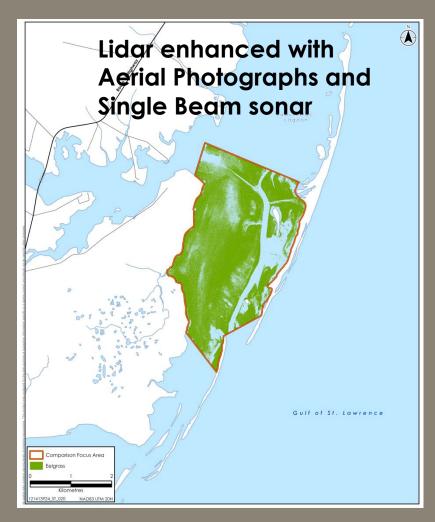


For eelgrass presence/absence, all methods are statistically indistinguishable from ground-truth data, as indicated by the Kappa Statistic (p < 0.001).



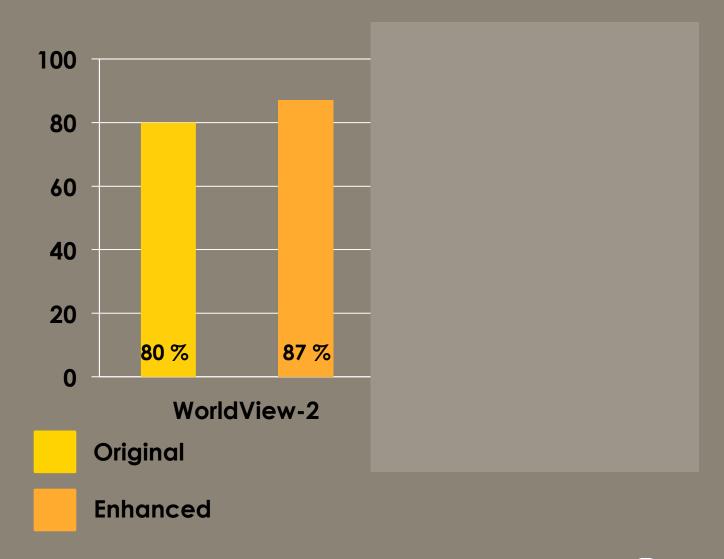
3 Results – Integrated Assessment







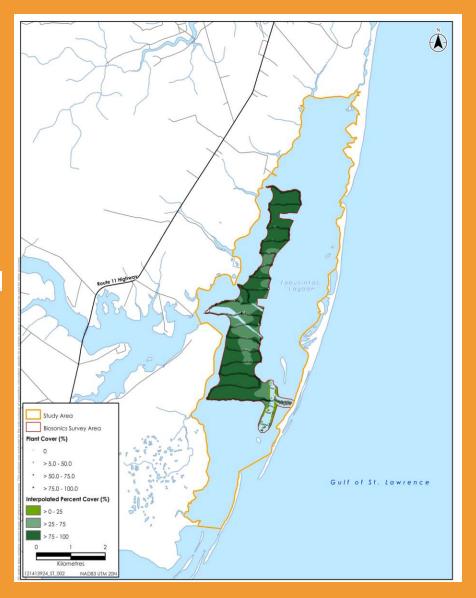
3 Results – Integrated Assessment





BioSonics

- Transect spacing not ideal (usually 50 m cells)
- If interpolated map acceptable, sonar is powerful
- High res PC, feature delineation, canopy height, bathymetric, and sediment composition maps not affected by water depth or water clarity
- \$ Cheapest option





Lidar

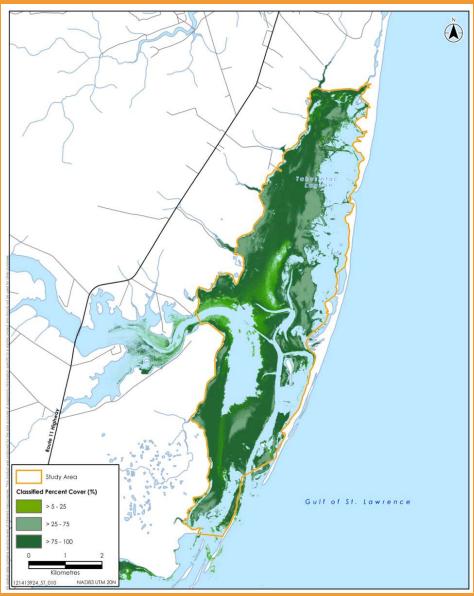
- Accurate
- Anomaly-spectral signature of affected by water depth and water clarity
- benefits from the number of data products that are collected simultaneously: water depth, water surface, intensity, and orthophotos
- Depth normalization
- \$\$\$ most expensive option





WV-2

- Accurate
- Also provides PC
- Anomaly-spectral signature of affected by water depth and water clarity
- ongoing sGSL research and Barrell et al. (2015) produced eelgrass maps at greater depths
- \$\$ 2nd cheapest option

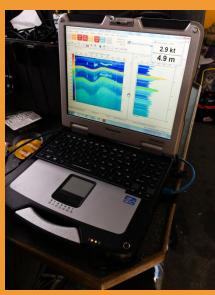




- Each technique accurate yet each methodology had its own strengths and limitations.
- Depending on study goals, any one or a combination of these methods could produce reliable maps











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